

# Predicate Abstraction

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# Abstraction and Concretization

- $\vec{\mathcal{V}} = (x_0, \dots, x_{n-1})$  program variables
- $\mathcal{S}$ : set of concrete program states
  - ▶ Example:  $\vec{\mathcal{V}} = (x_0, x_1)$ ,  $\mathcal{S} = \{(4, 5), (1, 2), (-7, 8)\}$
- $\mathcal{P} = \{P_0, \dots, P_{m-1}\}$  finite set of predicates on program variables
  - ▶ Example  $\mathcal{P} = \{P_0, P_1, P_2\}$ ,  $P_0 = \text{false}$ ,  $P_1 = x_1 > 0$ ,  $P_2 = x_0 < x_1$
- $\mathcal{A} = 2^{\mathcal{P}}$ : abstract domain
- Abstraction function  $\alpha : 2^{\mathcal{S}} \rightarrow \mathcal{A}$ 
$$\alpha(c) = \{P_i | \forall \vec{\mathcal{V}} \in c. P_i(\vec{\mathcal{V}})\}$$
- Concretization function  $\gamma : \mathcal{A} \rightarrow 2^{\mathcal{S}}$ 
$$\gamma(a) = \{\vec{\mathcal{V}} | \bigwedge_{P \in a} P(\vec{\mathcal{V}})\}$$

# Abstraction

## Example

- Let  $\mathcal{P} = \{x > y, x = 2\}$
- What is the abstraction after executing the following piece of code?

```
{true}  
val x: Int  
val y: Int  
x = y + 1
```

- $\forall x, y, x', y' \in \mathbb{Z}. (x' = y + 1) \wedge (y' = y) \rightarrow (x' > y')$  (valid)
- $\forall x, y, x', y' \in \mathbb{Z}. (x' = y + 1) \wedge (y' = y) \rightarrow (x' = 2)$  (not valid)

The abstraction is  $\{(x > y)\}$

# Abstraction

## Example

- Let  $\mathcal{P} = \{x < 2\}$
- What is the abstraction after executing the following piece of code?

$$\begin{array}{l} \{x = 2\} \\ \text{if } (x > 2) \ x = x - 1 \end{array}$$

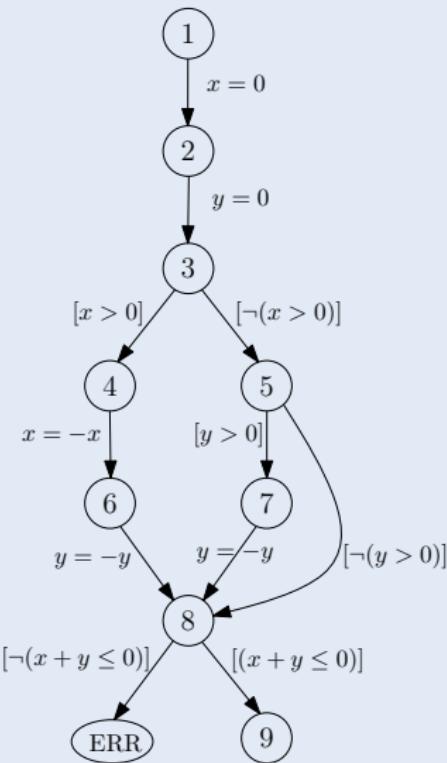
- $\forall x, x'. (x = 2) \wedge (x > 2) \wedge (x' = x - 1) \rightarrow (x' < 2)$   
 $\equiv \forall x, x'. \perp \rightarrow (x' < 2)$  (valid)
- The abstraction in this case : $\{(x < 2)\}$
- The predicate  $\perp$  is usually included in  $\mathcal{P}$

# Abstract Reachability Tree

- Abstract state  $(l, \psi)$ 
  - ▶  $l$ : location in control flow graph
  - ▶  $\psi$ : predicate abstraction
- Abstract reachability tree (ART) is a tree  $G = (V_{\mathcal{A}}, \rightarrow, l)$ 
  - $V_{\mathcal{A}}$  is a set of abstract states
  - $\rightarrow \subseteq V_{\mathcal{A}} \times V_{\mathcal{A}}$  is the transition relation
    - ▶ Let  $c$  be the command between  $l_i$  and  $l_j$  in the CFG
    - ▶  $((l_i, \psi), (l_j, \phi)) \in \rightarrow$  if  $\phi = sp^{\#}(\psi, c)$
  - $l \in V_{\mathcal{A}}$  is the initial abstract state
- $(l_i, \psi)$  is leaf if there exists another node  $(l_j, \phi)$  in the tree such that  
 $\models \psi \rightarrow \phi$

# ART Example

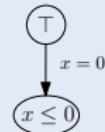
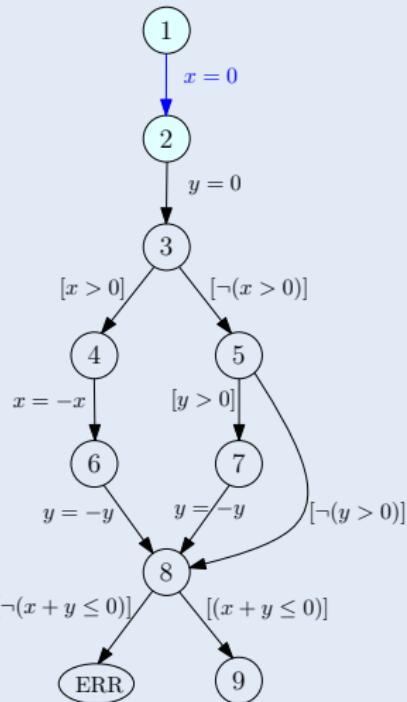
## Control Flow Graph



```
var x = 0
var y = 0
if( x > 0 ) {
    x = -x
    y = -y
} else {
    if( y > 0 ) y = -y
}
assert(x + y <= 0)
```

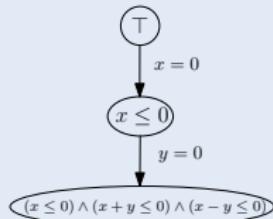
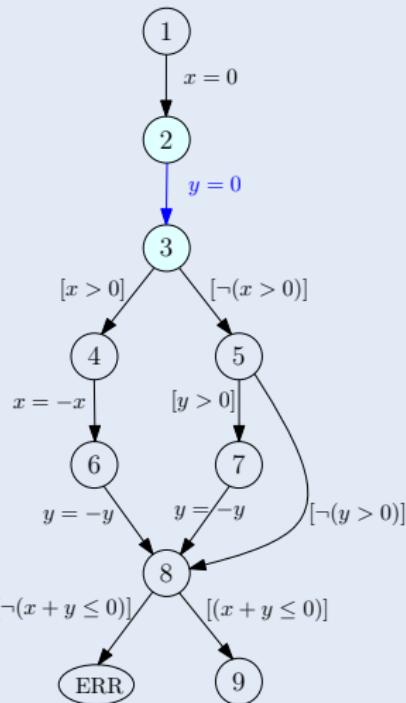
# ART Example

$$\mathcal{P} = \{\perp, (x \leq 0), (x + y \leq 0), (x - y \leq 0)\}$$



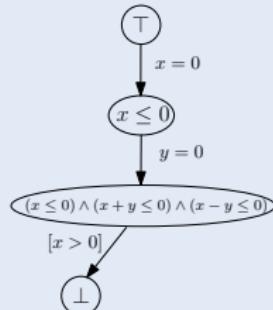
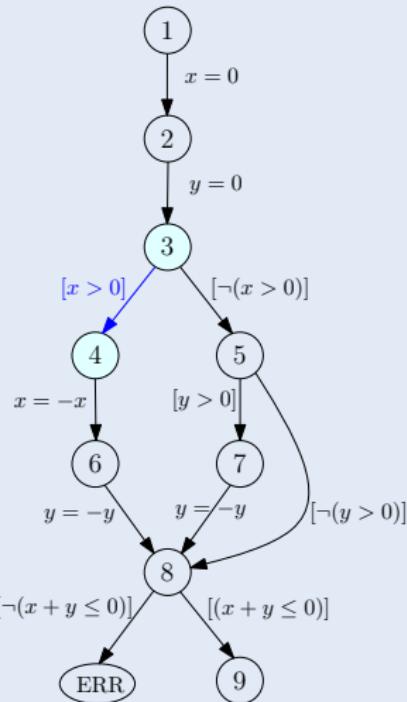
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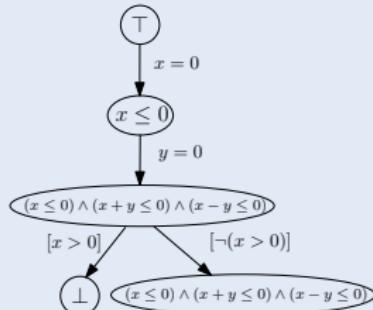
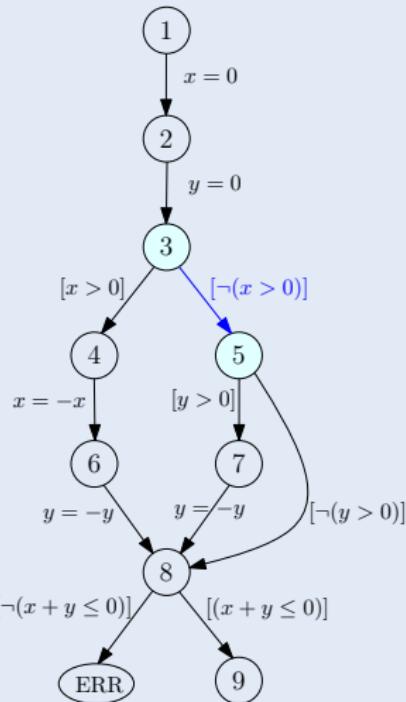
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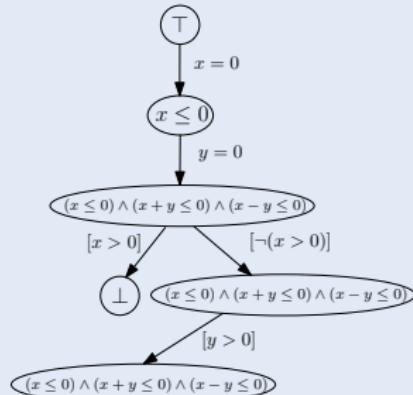
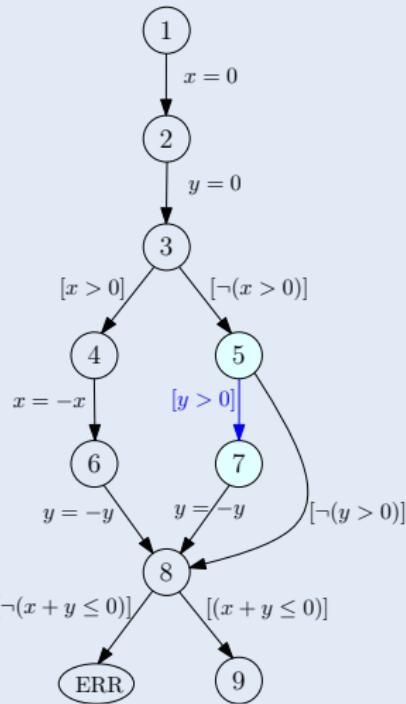
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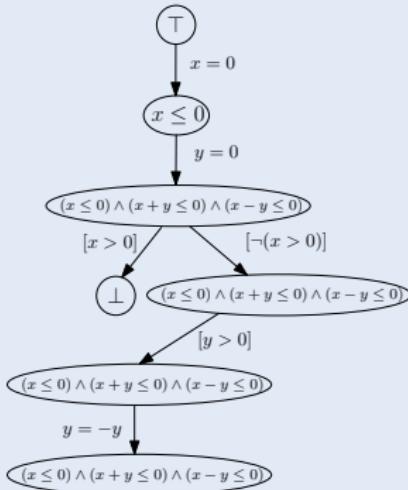
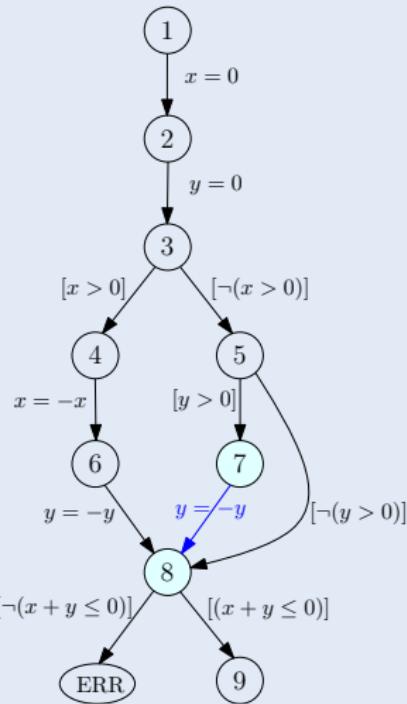
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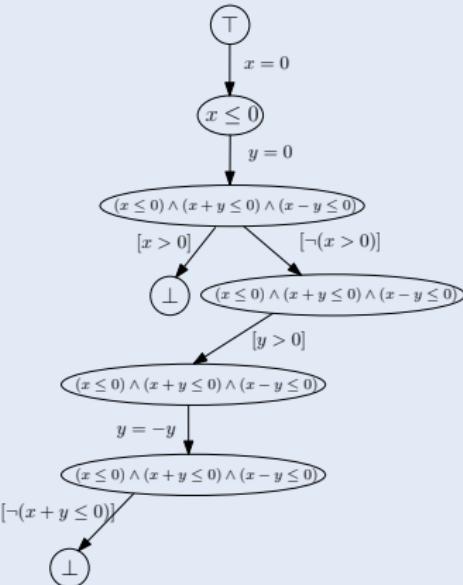
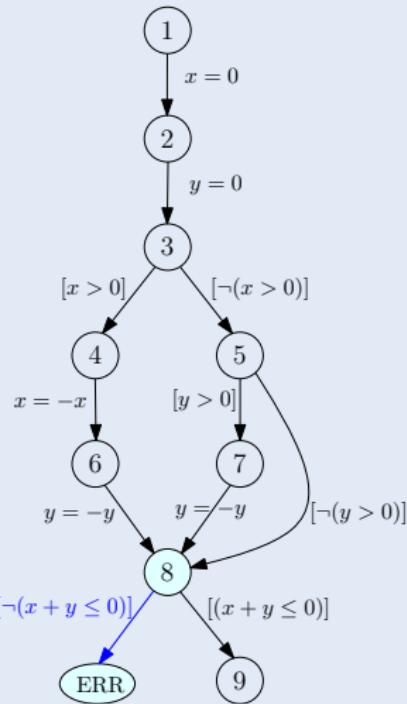
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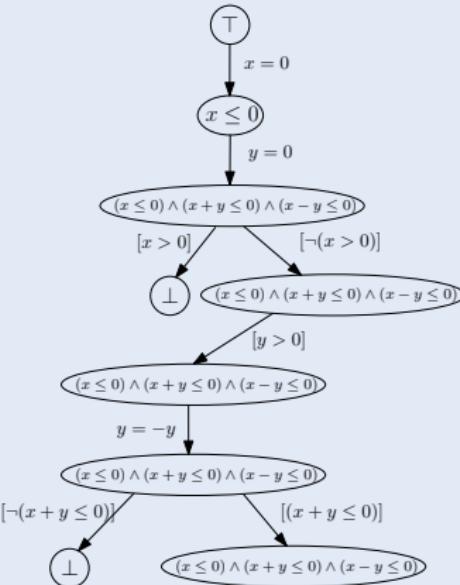
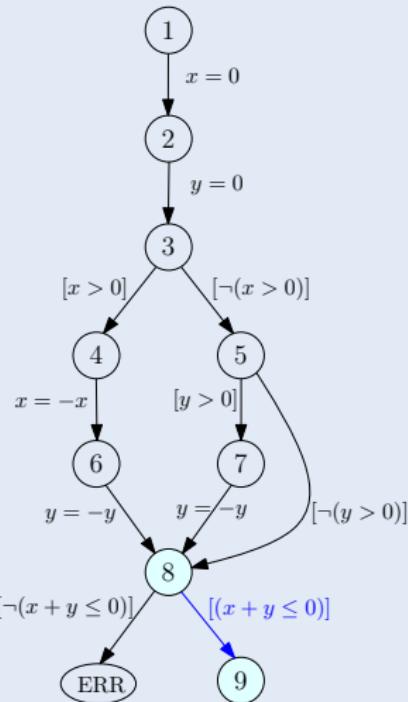
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