Application of Carathéodory bounds for integer cones in verification

Ruzica Piskac

Presentation of papers:

- Friedrich Eisenbrand, Gennady Shmonin: Carathéodory bounds for integer cones. Oper. Res. Lett. 34(5): 564-568 (2006)
- 2 Ruzica Piskac, Viktor Kuncak: Linear Arithmetic with Stars. In Proceedings of CAV 2008, to appear.

Mathematical models and algorithms for decision-making support

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Friedrich Eisenbrand, Gennady Shmonin: Carathéodory bounds for integer cones Oper. Res. Lett. 34(5): 564-568 (2006)

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Basic Definitions

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Definition

Let $S \in \mathbb{Z}^d$ be a finite set of integer vectors. The integer cone of S is the set

$$\mathsf{cone}(X) = \{\lambda_1 x_1 + \ldots + \lambda_n x_n \mid n \ge 0; x_i \in S; \lambda_i \in \mathbb{Z}; \lambda_i \ge 0\}$$

Definition

- For a vector x, the infinity norm is $||x||_{\infty} = \max\{|x_1|, \dots, |x_n|\}$
- For a set of vectors *S*, let M_S denote a number $M_S = \max_{x \in S} ||x||_{\infty}$

Problem Formulation

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Question we want to answer

Let $X \subseteq \mathbb{Z}^d$ be a set of integer vectors and let $b \in \text{cone}(X)$.

- Question: how many vectors from *X* are needed to generate *b*?
- (If those would be vectors with real coefficients, Carathéodory theorem states that *b* is generated with at most *d* vectors)

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Theorem

Let $X \subseteq \mathbb{Z}^d$ be a set of integer vectors and let $b \in \text{cone}(X)$. If $|X| > d \log_2(2|X|M_x + 1)$, then there exists a proper subset $\tilde{X} \subset X$ such that $b \in \text{cone}(\tilde{X})$.

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• assume that
$$b = \sum_{x \in X} \lambda_x x, \ \lambda_x > 0$$

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- for every subset S, $||\sum_{x \in S} x||_{\infty} \le |X|M_X$

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- the number of different vectors which are representable as the sum of vectors of S ⊆ X is bounded by (2|X|M_x + 1)^d, because coordinates are in {-|X|M_x,..., |X|M_x}

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- the number of different vectors which are representable as the sum of vectors of $S \subseteq X$ is bounded by $(2|X|M_x + 1)^d$, because coordinates are in $\{-|X|M_X, \dots, |X|M_X\}$
- theorem assumption: 2^{|X|} > (2|X|M_x + 1)^d ⇒ there are two different subsets A, B such that ∑_{x∈A} x = ∑_{x∈B} x

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Proof.

so far: assume b = ∑_{x∈X} λ_xx, λ_x > 0; there are two different disjoint subsets A, B such that ∑_{x∈A} x = ∑_{x∈B} x

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•
$$b = \sum_{x \in X} \lambda_x x = \sum_{x \in X \setminus A} \lambda_x x + \sum_{x \in A} \lambda_x x$$

 $= \sum_{x \in X \setminus A} \lambda_x x + \sum_{x \in A} (\lambda_x - \lambda) x + \lambda \sum_{x \in A} x$
 $= \sum_{x \in X \setminus A} \lambda_x x + \sum_{x \in A} (\lambda_x - \lambda) x + \lambda \sum_{x \in B} x$
 $= \sum_{x \in X} \mu_x x$

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Proof.

• so far: assume $b = \sum_{x \in X} \lambda_x x$, $\lambda_x > 0$; there are two different distinct subsets *A*, *B* such that $\sum_{x \in A} x = \sum_{x \in B} x$; $b = \sum_{x \in X} \mu_x x$, where

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• so far: assume $b = \sum_{x \in X} \lambda_x x$, $\lambda_x > 0$; there are two different distinct subsets A, B such that $\sum_{x \in A} x = \sum_{x \in B} x$; $b = \sum_{x \in X} \mu_x x$, where • $\mu_x = \begin{cases} \lambda_x, & x \in X \setminus (A \cup B) \\ \lambda_x - \lambda, & x \in A \\ \lambda_x + \lambda, & x \in B \end{cases}$

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Proof.

 Let X̃ be a minimal subset such that b ∈ cone(X̃) and let us assume that |X̃| > 2d log₂(4dM_x)

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- contradicts minimality of \tilde{X}

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- $\Rightarrow d \log_2(2|X|M_x+1) < |X|$

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Definition

- Multiset (bag) is a collection of elements where an element can occur several times
- Formally, multiset *m* is a function *m* : *E* → {0, 1, 2, ...} (*E* - finite universe)

$$m_1 = \{a, a, b, b, b\} \Rightarrow m_1(a) = 2 m_1(b) = 3 m_1(c) = 0$$

$$m_2 = \{a, b, c\} \Rightarrow m_2(a) = 1 m_2(b) = 1 m_2(c) = 1$$

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Example

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 $m_2 = \{a, b, c\} \Rightarrow m_2(a) = 1 m_2(b) = 1 m_2(c) = 1$

Selected operations and relations on multisets:

• Plus
$$(m_1 \uplus m_2)(e) = m_1(e) + m_2(e)$$

 $m_1 \uplus m_2 = \{a, a, b, b, b, b, c\}$

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Selected operations and relations on multisets:

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- Intersection $(m_1 \cap m_2)(e) = \min\{m_1(e), m_2(e)\}$
- Subset $m_1 \subseteq m_2 \iff \forall e. m_1(e) \le m_2(e)$

Multisets in Software Analysis and Verification: Overview



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Multisets in Software Analysis and Verification: Example

Example

```
public void add(Object x)
ensures List = old List \ {x}
{
    Node n = new Node();
    n.data = x;
    n.next = first;
    first = n;
}
```

• Formula expressing the correctness of insertion:

 $|\mathbf{x}| = \mathbf{1} \rightarrow |\mathbf{L} \uplus \mathbf{x}| = |\mathbf{L}| + \mathbf{1}$

 To prove that it is valid, it is equivalent to show that its negation is unsatisfiable:

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 $|\textbf{\textit{x}}| = \textbf{1} \land |\textbf{\textit{L}} \uplus \textbf{\textit{x}}| \neq |\textbf{\textit{L}}| + \textbf{1}$

Decision Procedure: Overview

- reduce to normal form
- 2 replace multiset sums with "star" operator
- find semilinear sets characterizing the set of solutions of formulas under the sum
- generate PA formula for the results of sums
- check satisfiability of resulting formula

Presburger Arithmetic

Presburger Arithmetic (PA) is an arithmetic of natural numbers $(\mathbb{N}, \leq, +)$, without multiplication. It is decidable and there are decision procedures for deciding PA formulas.

Example

• express all multiset expressions using ∀e. F



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 - $|\mathbf{x}| = 1 \land |L \uplus \mathbf{x}| \neq |L| + 1$

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Example

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•
$$|\mathbf{x}| = 1 \land |L \uplus \mathbf{x}| \neq |L| + 1$$

• $|\mathbf{x}| = 1 \land |\mathbf{y}| \neq |L| + 1 \land \mathbf{y} = L \uplus \mathbf{x}$

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Example

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$$|\mathbf{x}| = 1 \land |L \uplus \mathbf{x}| \neq |L| + 1$$

•
$$|\mathbf{x}| = 1 \land |\mathbf{y}| \neq |L| + 1 \land \mathbf{y} = L \uplus \mathbf{x}$$

•
$$|\mathbf{x}| = 1 \land |\mathbf{y}| \neq |L| + 1 \land \forall e. \ \mathbf{y}(e) = L(e) + \mathbf{x}(e)$$

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- express all multiset expressions using ∀e. F
- group all sums into one, using vectors: $\sum t_1 = k_1 \land \sum t_2 = k_2 \rightsquigarrow \sum (t_1, t_2) = (k_1, k_2)$

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- express all multiset expressions using ∀e. F
- group all sums into one, using vectors: $\sum t_1 = k_1 \land \sum t_2 = k_2 \rightsquigarrow \sum(t_1, t_2) = (k_1, k_2)$ • $\sum x(e) = 1 \land \sum y(e) \neq \sum L(e) + 1 \land$ $\forall e. y(e) = L(e) + x(e)$

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- express all multiset expressions using ∀e. F
- group all sums into one, using vectors: $\sum t_1 = k_1 \land \sum t_2 = k_2 \rightsquigarrow \sum(t_1, t_2) = (k_1, k_2)$ • $\sum x(e) = 1 \land \sum y(e) \neq \sum L(e) + 1 \land$ $\forall e. \ y(e) = L(e) + x(e)$ • $\sum x(e) = 1 \land \sum y(e) = k_1 \land \sum L(e) = k_2 \land k_1 \neq k_2 + 1 \land$ $\forall e. \ y(e) = L(e) + x(e)$

Example

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 - $\sum_{\forall e, y(e)} x(e) = 1 \land \sum_{\forall e, y(e)} y(e) \neq \sum_{\forall e, y(e)} L(e) + 1 \land$
 - $\sum x(e) = 1 \land \sum y(e) = k_1 \land \sum L(e) = k_2 \land k_1 \neq k_2 + 1 \land \forall e. y(e) = L(e) + x(e)$

• $k_1 \neq k_2 + 1 \land$ (1, k_1, k_2) = $\sum (x(e), y(e), L(e)) \land \forall e. y(e) = L(e) + x(e)$

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- replace multiset constraints with integer constraints enriched with "star" operator
 - $k_1 \neq k_2 + 1 \land$ $(1, k_1, k_2) = \sum (x(e), y(e), L(e)) \land \forall e. y(e) = L(e) + x(e)$ • $k_1 \neq k_2 + 1 \land (1, k_1, k_2) \in \{(x, y, L) \mid y = L + x\}^*,$ where $S^* = \{x_1 + \ldots + x_n \mid x_i \in S \land n \ge 0\}$ Note: $S^* = \text{cone}(S)$

Multiset Elimination

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Theorem

A formula in the sum normal form:

$$P \land (u_1,\ldots,u_n) = \sum_{e\in E} (t_1,\ldots,t_n) \land \forall e.F$$

is equisatisfiable with the formula

$$P \land (u_1,\ldots,u_n) \in \{(t'_1,\ldots,t'_n) \mid F; x_1,\ldots,x_p \in \mathbb{N}\}^*$$

where t'_i is t_i in which each $m_k(e)$ is replaced by fresh var x_k and $C^* = \{v_1 + \ldots + v_n \mid v_i \in C \land n \ge 0\}$

$$(1, k_1, k_2) = \sum (x(e), y(e), L(e)) \land \forall e. y(e) = L(e) + x(e)$$

 $(1, k_1, k_2) \in \{(x, y, L) \mid y = L + x; y, x, L \in \mathbb{N}\}^*$

Multiset Elimination

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Example

$$(1, k_1, k_2) = \sum (x(e), y(e), L(e)) \land \forall e. y(e) = L(e) + x(e)$$

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Proof.

 $\begin{array}{l} \Leftarrow \text{ assume that } (u_1, \ldots, u_n) = (t_1^1, \ldots, t_n^1) + \ldots + (t_1^k, \ldots, t_n^k) \\ \text{We define set } E \text{ to have } k \text{ elements: } E = \{e_1, \ldots, e_k\} \\ m_i(e_j) \text{ has the value of corresponding } x_i^j. \\ \Rightarrow \text{ analogous, except that } E \text{ is given} \end{array}$

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Question

Can we describe $(u_1, \ldots, u_n) \in \{(t_1, \ldots, t_n) \mid F\}^*$ by PA formula?

Definition

Let $C_1, C_2 \subseteq \mathbb{N}^k$ be sets of vectors of non-negative integers. We define:

 $\begin{array}{l} C_1 + C_2 = \{x_1 + x_2 \mid x_1 \in C_1 \land x_2 \in C_2\} \\ C_1^* = \{x_1 + \ldots + x_n \mid x_i \in C_1 \land n \geq 0\} \end{array}$

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Semilinear sets

Linear set = set of form $\{x\} + C^*$ for $x \in \mathbb{N}^n$ and $C \subseteq \mathbb{N}^n$ finite Semilinear set = finite union of linear sets

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Semilinear sets

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Example

 $LS(2;10) = \{2, 12, 22, 32, 42, 52, 62, \ldots\}$ $LS(5;3,5) = \{5, 8, 10, 11, 13, 14, 15, 16, 18, \ldots\}$

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- In [GinsburgSpanier1968] it was shown:
 - semilinear sets are closed under union, intersection and negation
 - a solution of PA formula is a semilinear set

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$$(u_1, \ldots, u_n) \in \{(t'_1, \ldots, t'_n) \mid F\}^*$$

is effectively expressible as PA formula

Example (Continued)

Example

• $k_1 \neq k_2 + 1 \land (1, k_1, k_2) \in \{(x, y, L) \mid y = L + x, y, x, L \in \mathbb{N}\}^*$

Example (Continued)

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- $k_1 \neq k_2 + 1 \land (1, k_1, k_2) \in \{(x, y, L) \mid y = L + x, y, x, L \in \mathbb{N}\}^*$
- {(x, y, L) | y = L + x, y, x, L ∈ N}* is described with semilinear set LS((0, 0, 0); (1, 1, 0), (0, 1, 1))

Example (Continued)

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Example

- $k_1 \neq k_2 + 1 \land (1, k_1, k_2) \in \{(x, y, L) \mid y = L + x, y, x, L \in \mathbb{N}\}^*$
- {(x, y, L) | y = L + x, y, x, L ∈ N}* is described with semilinear set LS((0, 0, 0); (1, 1, 0), (0, 1, 1))
- (1, k₁, k₂) ∈ {(x, y, L) | y = L + x, y, x, L ∈ ℕ}* is equisatisfiable with:

 $(1, k_1, k_2) = \lambda_1 (1, 1, 0) + \lambda_2 (0, 1, 1)$

• formula derived during the proof:

$$\exists \mu_i, \lambda_{ij}. (u_1, \dots, u_n) = \sum_{i=1}^k (\mu_i a_i + \sum_{j=0}^{q_i} \lambda_{ij} b_{ij}) \land$$

$$\bigwedge_{i=1}^{n} (\mu_i = 0 \implies \sum_{j=0}^{n} \lambda_{ij} = 0)$$



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Bounds on Solution Size

Our exponential formula looks like this:

$$P \wedge (u_1, \ldots, u_n) = \sum_{i=1}^k (\mu_i a_i + \sum_{j=1}^{q_i} \lambda_{ij} b_{ij}) \wedge \bigwedge_{i=1}^k (\mu_i = 0 \implies \sum_{j=1}^{q_i} \lambda_{ij} = 0)$$

Pottier 1991 - the solution set of Ax = b is a semilinear set with a_i , b_{ij} with polynomially many bits

Papadimitriou 1981 - bounds on PA formula solutions

- solution vector (u₁,..., u_n) has polynomially many bits, even for our exponential formulas!
- reason: formulas are exponential, but have polynomially many conjuncts

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Constructing Polynomially Large Formulas

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Picking Subset of a_i, b_{ij}

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Our exponential formula looks like this:

$$P \wedge (u_1, \ldots, u_n) = \sum_{i=1}^k (\mu_i a_i + \sum_{j=1}^{q_i} \lambda_{ij} b_{ij}) \wedge \bigwedge_{i=1}^k (\mu_i = 0 \implies \sum_{j=1}^{q_i} \lambda_{ij} = 0)$$

Theorem

If u is generated by a_i , b_{ij} , then it is generated by polynomial subset of them.

• proof generalizes results by Eisenbrand, Shmonin (2006)

Proof



- apply Eisenbrand-Shmonin theorem as black box on b_{ij} vectors
- there are only polynomially vectors b_{ij} needed to represent b
- join them with associated a_i vectors
- apply Eisenbrand-Shmonin theorem on remaining a_i vectors



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Idea: Guess *a_i*, *b_{ij}*?

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Problem: how to check if a guessed vector is one of a_i or b_{ij} ?

Approach: instead of guessing a_i , b_{ij} , guess solutions c where F(c)

Result:

$$P \wedge \vec{u} = \{ \vec{v} \mid F \}^*$$

is equisatisfiable with

$$P \wedge \vec{u} = \sum_{i=1}^{Q} \lambda_i \vec{v}_i \wedge \bigwedge_{i=1}^{Q} F(\vec{v}_i)$$

where Q polynomially large, can compute it from F

Last Hurdle

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$$P \wedge \vec{u} = \sum_{i=1}^{\mathsf{Q}} \lambda_i \vec{v}_i \wedge \bigwedge_{i=1}^{\mathsf{Q}} F(\vec{v}_i)$$

Polynomially large formula.

- but it multiplies variables λ_i , v_i not linear?
- nevertheless: vectors bounded, can expand multiplication

Result: NP completeness!

Conclusions

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Presented

- result on Carathéodory bounds for integer cones
- language used for reasoning about properties of data structures
- new decision procedure for quantifier-free multiset formulas with cardinality operator
- optimal complexity result: NP-completeness
- algorithm: generating polynomially large PA formulas