# Lecture 9 How to make a sound type system

#### Why types are good

Prevent errors: many simple errors caught by types

Ensure memory safety or other desired properties

Document the program (purpose of parameters)

Make it easier to change

Make compilation more efficient: remove checks, specialize

#### An unsound (broken) type system

A type system that aims to ensure some property but, in fact, fails.

For example: suppose we have a system that aims to ensure that if parameter is of type Int, then it is only invoked with values of type Int. But we find a (tricky) program that passes the type checker but ends up invoking the function with the reference to a string. This is unsoundness.

Sometimes unsoundness is (somewhat) intentional compromise:

- type casts in C
- covariance for function arguments and arrays

Sometimes unintentional (unsoundness type system bugs)

#### Goal today

#### Define precisely a small language:

- its abstract syntax (as certain math expressions)
- its operational semantics (interpreter written in math)
- its type rules

Show that our type system prevents certain kinds of errors

Define relation  $r \subseteq \mathbb{Z} \times \mathbb{Z}$  using these inductive rules.

$$\frac{(x,y) \in r}{(x,y+1) \in r} \text{ (increase right)}$$

$$\frac{(x,y) \in r}{(x+1,y+1) \in r} \text{ (incease both)}$$

$$\frac{(x,y) \in r}{(x-1,y-1) \in r} \text{ (decrease both)}$$

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$$r = \{(x, y) \mid x = 0 \lor y = 0\}$$
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- r = Z × Z ? Yes

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Which relations satisfy these rules?

• 
$$r = \{(x, y) \mid x = 0 \lor y = 0\}$$
 ? No

► 
$$r = \{(x, y) \mid x \le 0 \land 0 \le y\}$$
 ? No  
►  $r = \mathbb{Z} \times \mathbb{Z}$  ? Yes

What is the **smallest** relation (wrt.  $\subseteq$ )?

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$$r = \{(x, y) \mid x = 0 \lor y = 0\}$$
 ? No

$$r = \{(x, y) \mid x < 0 \land 0 < y\}$$
 ? No

$$r = \mathbb{Z} \times \mathbb{Z}$$
? Yes

What is the **smallest** relation (wrt.  $\subseteq$ )?  $r = \{(x, y) \mid x \le y\}$ 

### Example derivation of $(-3, -1) \in r$

$$(0,0) \in r$$

$$(0,1) \in r$$

$$(0,2) \in r$$

$$(-1,1) \in r$$

$$(-2,0) \in r$$

$$(-3,-1) \in r$$

$$\frac{r}{(0,0)\in r} \text{ (zero)}$$

$$\frac{(x,y) \in r}{(x,y+1) \in r}$$
 (increase right)

$$\frac{(x,y) \in r}{(x+1,y+1) \in r}$$
 (incease both)

$$\frac{(x,y) \in r}{(x-1,y-1) \in r}$$
 (decrease both)

#### Inductively defined relations

We can use inductive rules to define type systems, grammars, interpreters, . . .

We define a relation *r* using **rules** of the form

$$\frac{t_1(\bar{x}) \in r, \dots, t_n(\bar{x}) \in r}{t(\bar{x}) \in r}$$

where  $t_i(\bar{x}) \in r$  are assumptions and  $t(\bar{x}) \in r$  is the conclusion. When n = 0 (no assumptions), the rule is called an axiom.

A derivation tree has nodes marked by tuples  $t(\bar{a})$  for some specific values  $\bar{a}$  of  $\bar{x}$ .

We define relation r as the set of all tuples for which there exists a derivation tree. This is the smallest relation that satisfies the rules.

#### Amyrli language

Tiny language similar to one in the project. Works only on integers and booleans.

(Initial) program is a pair  $(e_{top}, t_{top})$  where

- e<sub>top</sub> is the top-level environment mapping function names to function definitions
- $ightharpoonup t_{top}$  is the top-level term (expression) that starts execution

Function definition for a given function name is a tuple of: parameter list  $\bar{x}$ , parameter types  $\bar{\tau}$ , expression representing function body t, and result type  $\tau_0$ .

Expressions are formed by invoking primitive functions  $(+,-,\leq,\&\&)$ , invocations of defined functions, or **if** expressions.

No local val definitions nor match. e will remain fixed

#### Amyrli: abstract syntax of terms

$$t := \textit{true} \mid \textit{false} \mid \textit{c}_\textit{l} \mid \textit{f}(t_1, \dots, t_n) \mid \textit{if} (t) \ t_1 \ \textit{else} \ t_2$$

#### where

- ▶  $c_l$  ∈  $\mathbb{Z}$  denotes integer constant
- f denotes either application of a user-defined function or one of the primitive operators

#### Program representation as a mathematical structure

```
p_{fact} = (e, fact(2))
where e(fact) = (n, Int, if (n \le 1) 1 else n * fact(n - 1), Int)
```

#### Operational semantics of Amyrli: if expression

We specify the result of executing the program as an inductively defined binary (infix) relation " $\sim$ " on programs. If the top-level expression becomes a constant after some number of steps of  $\sim$ , we have computed the result:  $t \stackrel{*}{\sim} c$  Rules for **if**:

$$\frac{b \rightsquigarrow b'}{(\mathbf{if}\ (b)\ t_1\ \mathbf{else}\ t_2) \rightsquigarrow (\mathbf{if}\ (b')\ t_1\ \mathbf{else}\ t_2)}$$

$$\overline{(\text{if }(\textit{true})\ t_1\ \text{else}\ t_2) \leadsto t_1}$$

$$\overline{\text{(if } (false) } t_1 \text{ else } t_2) \sim t_2$$

#### Operational semantics of Amyrli: primitives

Logical operators:

Arithmetic:

#### Operational semantics: user function f

If  $c_1, \ldots, c_{i-1}$  are constants, then (as expected in call-by-value)

$$\frac{t_i \rightsquigarrow t_i'}{f(c_1,\ldots,c_{i-1},t_i,\ldots) \rightsquigarrow f(c_1,\ldots,c_{i-1},t_i',\ldots)}$$

Let the environment e define f by  $e(f) = ((x_1, ..., x_n), \bar{\tau}, t_f, \tau_0)$ 

- $(x_1,\ldots,x_n)$  is the list of formal parameters of f
- t<sub>f</sub> is the body of the function f

Then we can apply rule

$$\overline{f(c_1,\ldots,c_n)} \sim t_f[x_1 := c_1,\ldots,x_n := c_n]$$

In general, if t is term, then  $t[x_1 := t_1, \dots, x_n := t_n]$  denotes result of substituting (replacing) in t each variable  $x_i$  by term  $t_i$ .

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fact(2) \sim
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fact(2) \sim

if (2 \le 1) \ 1 \ else \ 2 * fact(2 - 1) \sim

if (false) \ 1 \ else \ 2 * fact(2 - 1) \sim

2 * fact(2 - 1) \sim

2 * fact(1) \sim

2 * (if (1 \le 1) \ 1 \ else \ 1 * fact(1 - 1)) \sim
```

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              fact(2) \sim
             if (2 < 1) 1 else 2 * fact(2 - 1) \sim
             if (false) 1 else 2 * fact(2-1) \sim
             2 * fact(2-1) \sim
             2 * fact(1) \sim
             2*(if (1 \le 1) 1 else 1*fact(1-1)) \sim
             2 * (if (true) 1 else 1 * fact(1-1)) \sim
             2 * 1 ~
```

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             2 * (if (true) 1 else 1 * fact(1-1)) \sim
             2 * 1 ~
```

#### Getting stuck

If program makes no sense, we have no rule to define its evaluation.

Example: consider this top-level expression:

the expression 5 cannot be evaluated further and is a constant, but there are no rules for when arguments of **if** is a number constant, only rules for boolean constants.

Such programs, that are not constants and have no applicable rules, are called **stuck**, because no further steps are possible.

Stuck programs indicate errors. Type checking is a way to detect them **statically**, without trying to (dynamically) execute a program and see if it will get stuck or produce result.

#### Type Rules: Program

After the definition of operational semantics, we define type rules (also inductively).

Given initial program (e, t) define

$$\Gamma_0 = \{ (f, \tau_1 \times \cdots \times \tau_n \to \tau_0) \mid (f, \neg, (\tau_1, \dots, \tau_n), t_f, \tau_0) \in \mathbf{e} \}$$

We say program type checks if the top-level expression type checks:

$$\Gamma_0 \vdash t : \tau$$

and each function body type checks:

$$\Gamma_0 \oplus \{(x_1,\tau_1),\ldots,(x_n,\tau_n)\} \vdash t_f : \tau_0$$

for each  $(f, (x_1, ..., x_n), (\tau_1, ..., \tau_n), t_f, \tau_0) \in e$ 

#### Type Rules are as Usual

$$\frac{\Gamma \vdash b : \textit{Bool}, \quad \Gamma \vdash t_1 : \tau, \quad \Gamma \vdash t_2 : \tau}{\Gamma \vdash (\textit{if } (b) \ t_1 \ \textit{else} \ t_2) : \tau} \\ \frac{\Gamma \vdash f : \tau_1 \times \dots \times \tau_n \rightarrow \tau_0, \quad \Gamma \vdash t_1 : \tau_1, \ \dots, \ \Gamma \vdash t_n : \tau_n}{\Gamma \vdash f(t_1, \dots, t_n) : \tau_0}$$

We treat primitives like applications of functions e.g.

 $+: \mathit{Int} \times \mathit{Int} \to \mathit{Int}$ 

 $\leq$  : Int  $\times$  Int  $\rightarrow$  Bool

&& :  $Bool \times Bool \rightarrow Bool$ 

#### Soundness through progress and preservation

Soundness theorem: if a program type checks, then its evaluation does not get stuck.

Proof uses the following two lemmas, which is a common approach:

progress: if a program type checks, it is not stuck: if

$$\Gamma \vdash t : \tau$$

then either t is a constant or there exists t' such that  $t \rightsquigarrow t'$ 

preservation: if a program type checks and makes one ~> step, the result again type checks here: type checks and has the same type: if

$$\Gamma \vdash t : \tau$$

and  $t \sim t'$  then

$$\Gamma \vdash t' : \tau$$

## Proof of progress and preservation - case of if

We prove conjunction of progress and preservation by induction on term t such that  $\Gamma \vdash t : \tau$ . The operational semantics defines the non-error cases of an interpreter, which makes case analysis. Consider **if**. By type checking rules, **if** can only type check if its condition b type checks and has type Bool. By inductive hypothesis and progress either b is constant or it can be reduced to b'. If it is constant one of these rules apply:

$$\frac{(\text{if } (\textit{true}) \ t_1 \ \text{else} \ t_2) \sim t_1}{(\text{if } (\textit{false}) \ t_1 \ \text{else} \ t_2) \sim t_2}$$

and the result, by type rule for **if**, has type  $\tau$ . If b' is not constant and the assumption of the rule

$$\frac{b \rightsquigarrow b'}{(\text{if } (b) \ t_1 \text{ else } t_2) \rightsquigarrow (\text{if } (b') \ t_1 \text{ else } t_2)}$$

applies so t also makes progress. Moreover, by preservation b' also has type Bool, so the entire expression can be typed as  $\tau$  by re-using the type derivations for  $t_1$  and  $t_2$ .

#### Progress and preservation - user defined functions

Following the cases of operational semantics, either all arguments of function have been evaluated to a constant, or some are not yet constant.

If they are not all constants, the case is as for the condition of **if**, so we establish progress and preservation.

Otherwise rule

$$\overline{f(c_1,\ldots,c_n)} \sim t_f[x_1 := c_1,\ldots,x_n := c_n]$$

applies, so progress is ensured. For preservation, we need to show

$$\Gamma \vdash t_f[x_1 := c_1, \dots, x_n := c_n] : \tau \tag{*}$$

where  $e(f) = ((x_1, \ldots, x_n), (\tau_1, \ldots, \tau_n), t_f, \tau_0)$  and  $t_f$  is the body of f. According to type rules  $\tau = \tau_0$  and  $\Gamma \vdash c_i : \tau_i$ .

#### Progress and preservation - substitution and types

Function f definition type checks, so  $\Gamma' \vdash t_f : \tau_0$  where  $\Gamma' = \Gamma \oplus \{(x_1, \tau_1), \dots, (x_n, \tau_n)\}.$ 

C onsider the type derivation tree for  $t_f$  and replace each use of  $\Gamma' \vdash x_i : \tau_i$  with  $\Gamma \vdash c_i : \tau_i$ . The result is a type derivation for (\*):

$$\Gamma \vdash t_f[x_1 := c_1, \ldots, x_n := c_n] : \tau \tag{*}$$

Therefore, the preservation holds in this case as well.