Lecture 4 Refinement, Equivalence, and Synthesis

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Local Mutable Variables

Local Variables

Assume our global variables are $V = \{x, z\}$ Program P introduces a local variable y inside a nested block:

$$x = x + 1$$
; {var y; $y = x + 3$; $z = x + y + z$ }; $x = x + z$

R(P) should be a relation between (x, y) and (x', y').

Each statement should be relation between variables in scope.

Inside the block we have variables $V_1 = \{x, y, z\}$. For assignment statement c: z = x + y + z,

R(c) is a relation between x, y, z and x', y', z'.

Convention: consider the initial values of variables to be arbitrary

$$R(y = x + 3; z = x + y + z) = y' = x + 3 \land z' = 2x + 3 + z \land x' = x$$

$$R(\{var\ y; y = x + 3; z = x + y + z\}) = z' = 2x + 3 + z \land x' = x$$



Local Variable Translation

 $R_V(P)$ is formula for P in the scope that has the set of variables P For example,

$$R_V(x=t) = x' = t \wedge \bigwedge_{v \in V \setminus \{x\}} v' = v$$

Then define

$$R_V(\{var\ y; P\}) = \exists y, y'. R_{V \cup \{y\}}(P)$$

Exercise: express havoc(x) using var.

$$R_V(havoc(x)) \iff R_V(\{var\ y;\ x=y\})$$

Exercise: give transformation that lifts all variables to be global



Expressing Specifications as Commands

Shorthand: Havoc Multiple Variables at Once

Variables $V = \{x_1, ..., x_n\}$ Translation of $R(havoc(y_1, ..., y_m))$:

$$\bigwedge_{v \in V \setminus \{y_1, \dots, y_m\}} v' = v$$

Exercise: the resulting formula is the same as for:

$$havoc(y_1); \ldots; havoc(y_n)$$

Thus, the order of distinct havoc-s does not matter.

Programs and Specs are Relations

program:
$$x = x + 2; y = x + 10$$

relation: $\{(x, y, z, x', y', z') \mid x' = x + 2 \land y' = x + 12 \land z' = z\}$
formula: $x' = x + 2 \land y' = x + 12 \land z' = z$

Specification:

$$z'=z\wedge \big(x>0\to (x'>0\wedge y'>0\big)$$

Adhering to specification is relation subset:

$$\{(x, y, z, x', y', z') \mid x' = x + 2 \land y' = x + 12 \land z' = z\}$$

$$\subseteq \{(x, y, z, x', y', z') \mid z' = z \land (x > 0 \rightarrow (x' > 0 \land y' > 0))\}$$

Non-deterministic programs are a way of writing specifications



Writing Specs Using Havoc and Assume: Examples

Program variables $V = \{x, y, z\}$

Formula for relation (talks only about resulting state):

$$z' = z \wedge x' > 0 \wedge y' > 0$$

Corresponding program:

$$havoc(x, y)$$
; $assume(x > 0 \land y > 0)$

Formula for relation:

$$z' = z \wedge x' > x \wedge y' > y$$

Corresponding program?

Use local variables to store initial values.

```
{ var x0; var y0;

x0 = x; y0 = y;

havoc(x,y);

assume(x > x0 \&\& y > y0)

}
```

Writing Specs Using Havoc and Assume

```
Global variables V=\{x_1,\ldots,x_n\}
Specification F(x_1,\ldots,x_n,x_1',\ldots,x_n')
```

Becomes

```
{ var y_1, ..., y_n;

y_1 = x_1; ...; y_n = x_n;

havoc(x_1, ..., x_n);

assume(F(y_1, ..., y_n, x_1, ..., x_n)) }
```

Program Refinement and Equivalence

For two programs, define **refinement** $P_1 \sqsubseteq P_2$ iff

$$R(P_1) \rightarrow R(P_2)$$

is a valid formula.

(Some books use the opposite meaning of \sqsubseteq .)

As usual, $P_2 \supseteq P_1$ iff $P_1 \sqsubseteq P_2$.

▶ $P_1 \sqsubseteq P_2$ iff $\rho(P_1) \subseteq \rho(P_2)$

Define **equivalence** $P_1 \equiv P_2$ iff $P_1 \sqsubseteq P_2 \land P_2 \sqsubseteq P_1$

$$P_1 \equiv P_2 \text{ iff } \rho(P_1) = \rho(P_2)$$

Example for $V = \{x, y\}$

$$\{var\ x0; x0 = x; havoc(x); assume(x > x0)\} \supseteq (x = x + 1)$$

Proof: Use R to compute formulas for both sides and simplify.

$$x' = x + 1 \land y' = y \rightarrow x' > x \land y' = y$$



Stepwise Refinement Methodology

Stepwise Refinement Methodology

Start form a possibly non-deterministic specification P_0 Refine the program until it becomes deterministic and efficiently executable.

$$P_0 \supseteq P_1 \supseteq \ldots \supseteq P_n$$

Example:

$$havoc(x)$$
; $assume(x > 0)$; $havoc(y)$; $assume(x < y)$
 $\supseteq havoc(x)$; $assume(x > 0)$; $y = x + 1$
 $\supseteq x = 42$; $y = x + 1$
 $\supseteq x = 42$; $y = 43$

In the last step program equivalence holds as well

Monotonicity with Respect to Refinement

Theorem: if $P_1 \sqsubseteq P_2$ then $(P_1; P) \sqsubseteq (P_2; P)$ Version for relations: $(p_1 \subseteq p_2) \to (p_1 \circ p) \subseteq (p_2 \circ p)$

Theorem: if $P_1 \sqsubseteq P_2$ then $(P; P_1) \sqsubseteq (P; P_2)$ Version for relations: $(p_1 \subseteq p_2) \rightarrow (p \circ p_1) \subseteq (p \circ p_2)$

Theorem: if $P_1 \sqsubseteq P_2$ and $Q_1 \sqsubseteq Q_2$ then

$$(if (*)P_1 else Q_1) \sqsubseteq (if (*)P_2 else Q_2)$$

Version for relations:

$$(p_1 \subseteq p_2) \wedge (q_1 \subseteq q_2) \rightarrow (p_1 \cup q_1) \subseteq (p_2 \cup q_2)$$

Checking Commutativity and Idempotence

Associativity of Commands

Under what conditions on commands c_1, c_2 is

$$c_1; (c_2; c_3) \equiv (c_1; c_2); c_3$$

always

Commutativity of Commands

Under what conditions on commands c_1, c_2 is

$$c_1; c_2 \equiv c_2; c_1$$

In general, when the resulting relations are equal and formulas equivalent, i.e. iff

$$R(c_1; c_2) \iff R(c_2; c_1)$$

is a valid formula (true for all variables).

Example: does this hold?

$$(x = x + 1; y = x + 2) \equiv (y = x + 2; x = x + 1)$$

Show formulas for each sides—not equivalent:

$$x' = x + 1 \land y' = x + 3$$
 $x' = x + 1 \land y' = x + 2$



Examples of Commutativity of Commands

Show the formula for each example and check if the commutativity equivalence holds

Example 1:

$$(x = 2*x+7*z; y = 5*y+z) \equiv (y = 5*y+z; x = 2*x+7*z)$$

Can you state a generalization of the above example? Example 2:

$$(x = x + 1; x = x + 5) \equiv (x = x + 5; x = x + 1)$$

Requires knowing properties of +.

Preserving Domain in Refinement

What is the domain of a relation?

Given relation $r \subseteq A \times B$ for any sets A, B, we define domain of r as

$$dom(r) = \{a \mid \exists b. \ (a, b) \in r\}$$

when r is a total function, then dom(r) = A

a typical case if r is an entire program

Let
$$r = \{(\bar{x}, \bar{x}') \mid F\}$$
, $FV(F) \subseteq Var \cup Var'$, $Var' = \{x' \mid x \in Var\}$.
Then, $dom(r) = \{\bar{x} \mid \exists \bar{x}'.F\}$

computing domain = existentially quantifying over primed vars

Example: for $Var = \{x, y\}$, $R(x = x + 1) = x' = x + 1 \land y' = y$. The formula for the domain is: $\exists x', y'. \ x' = x + 1 \land y' = y$, which, after one-pint rule, reduces to true.

▶ All assignments have true as domain.



Preserving Domain

It is not interesting program development step $P \supseteq P'$ is P' is false, or is false for most inputs.

Example (
$$Var = \{x, y\}$$
)

$$(havoc(x); assume(x + x = y)) \supseteq (assume(y = 6); x = 3)$$

Refinement $P \supseteq Q$, ensures $R(Q) \to R(P)$. A consequence is $(\exists \bar{x}'.R(Q)) \to (\exists \bar{x}'.R(P))$.

We additionally wish to preserve the *domain* of the relation between \bar{x}, \bar{x}'

- if P has some execution from \bar{x} ending in x'
- then Q should also have some execution, ending in some (possibly different) x' (even if it has fewer choices)

$$(\exists \bar{x}'.R(P)) \leftrightarrow (\exists \bar{x}'.R(Q))$$

So, we want relations to be smaller or equal, but domains equal.



Domains in the Example

Consider our example $P \supseteq P'$

$$(havoc(x); assume(x + x = y)) \supseteq (assume(y = 6); x = 3)$$

- $P(P) = x' + x' = y \wedge y' = y$
- $R(P') = x' = 3 \land y' = 6 \land y' = y$

Does $P \supseteq P'$ really hold?

Now consider the right hand side:

- ▶ domain of *P* is $\exists x', y'.x' + x' = y \land y' = y$
- equivalent to: y%2 = 0
- ▶ domain of *P* is: $\exists x', y'.x' = 3 \land y' = 6 \land y' = y$
- equivalent to: y = 6

Does domain formula of P' imply the domain formula of P?



Preserving Domain: Exercise

Given P:

$$havoc(x)$$
; $assume(x + x = y)$

Find P_1 and P_2 such that

- \triangleright $P \supseteq P_1 \supseteq P_2$
- ▶ no two programs among P, P_1, P_2 are equivalent
- \triangleright programs P, P_1 and P_2 have equivalent domains
- \blacktriangleright the relation described by P_2 is a partial function

Complete Functional Synthesis

Synthesis from Relations

Software Synthesis Procedures Viktor Kuncak, Mikaël Mayer, Ruzica Piskac, Philippe Suter Communications of the ACM, Vol. 55 No. 2, Pages 103-111 http://doi.org/10.1145/2076450.2076472

Example of Synthesis

```
Input:
val (hours, minutes, seconds) = choose((h: Int, m: Int, s: Int) => (
  h * 3600 + m * 60 + s == totsec
  && 0 \le m && m < 60
  && 0 \le s && s < 60)
Output:
val (hours, minutes, seconds) = \{
val loc1 = totsec div 3600
val num2 = totsec + ((-3600) * loc1)
val loc2 = min(num2 div 60, 59)
val loc3 = totsec + ((-3600) * loc1) + (-60 * loc2)
 (loc1, loc2, loc3)
```

Complete Functional Synthesis

Domain-preserving refinement algorithm that produces a partial function

- assignment: res = choose x. F
- corresponds to: {var x; assume(F); res = x}
- we refine it preserving domain into: assume(D); res = t (where t does not have 'choose')

More abstractly, given formula F and variable x find

- ▶ formula D
- term t not containing x

such that, for all free variables:

- ▶ $D \rightarrow F[x := t]$ (t is a term such that refinement holds)
- ▶ $D \iff \exists x.F$ (D is the domain, says when t is correct)

Consequence of the definition: $D \iff F[x := t]$

From Quantifier Elimination to Synthesis

Quantifier Elimination

If \bar{y} is a tuple of variables not containing x, then

$$\exists x.(x = t(\bar{y}) \land F(x, \bar{y})) \iff F(t(\bar{y}), \bar{y})$$

Synthesis

choose
$$x.(x = t(\bar{y}) \land F(x, \bar{y}))$$

gives:

- precondition $F(t(\bar{y}), \bar{y})$, as before, but also
- program that realizes x, in this case, $t(\bar{y})$

Handling Disjunctions

We had

$$\exists x. (F_1(x) \lor F_2(x))$$

is equivalent to

$$(\exists x.F_1(x)) \lor (\exists x.F_2(x))$$

Now:

choose
$$x.(F_1(x) \vee F_2(x))$$

becomes:

if
$$(D_1)$$
 (choose $x.F_1(x)$) else (choose $x.F_2(x)$)

where D_1 is the domain, equivalent to $\exists x.F_1(x)$ and computed while computing *choose* $x.F_1(x)$.

Framework for Synthesis Procedures

We define the framework as a transformation

- from specification formula F to
- ▶ the maximal domain *D* where the result *x* can be found, and the program *t* that computes the result

 $\langle D \mid t \rangle$ denotes: the domain (formula) D and program (term) t Main transformation relation \vdash

choose
$$x.F \vdash \langle D \mid t \rangle$$

means

- ▶ $D \rightarrow F[x := t]$ (t is a term such that refinement holds)
- ▶ $D \iff \exists x.F \quad (D \text{ is the domain, says when } t \text{ is correct})$

Because F[x := t] implies $\exists x.F$, the above definition implies that D, F[x := t] and $\exists x.F$ are all equivalent.

Rule for Synthesizing Conditionals

$$\frac{\textit{choose } x.F_1 \vdash \langle D_1 \mid t_1 \rangle \quad \textit{choose } x.F_2 \vdash \langle D_2 \mid t_2 \rangle}{\textit{choose } x.(F_1 \lor F_2) \ \vdash \ \langle D_1 \lor D_2 \mid \textit{if } (D_1) \ t_1 \textit{ else } t_2 \rangle}$$

To synthesize the thing below the -, synthesize the things above and put the pieces together.

Test Terms Methods for Presburger Arithmetic Synthesis

Recall that the most complex step in QE for PA was replacing

$$\exists x.F_1(x)$$

with

$$\bigvee_{k=1}^{L}\bigvee_{i=1}^{N}F_{1}(a_{k}+i)$$

Now we transform *choose* $x.F_1(x)$ first into:

choose
$$x$$
. $\bigvee_{k=1}^{L}\bigvee_{i=1}^{N}(x=a_k+i\wedge F_1(x))$

Then apply:

- rule for conditionals
- one-point rule

Synthesis using Test Terms

choose
$$x$$
. $\bigvee_{k=1}^{L}\bigvee_{i=1}^{N}(x=a_k+i\wedge F_1)$

produces the same precondition as the result of QE, and the generated term is:

$$\begin{array}{l} \textit{if } (F_1[x:=a_1+1]) \ a_1+1 \\ \textit{elseif } (F_1[x:=a_1+2]) \ a_1+2 \\ \dots \\ \textit{elseif } (F_1[x:=a_k+i]) \ a_k+i \\ \dots \\ \textit{elseif } (F_1[x:=a_L+N]) \ a_L+N \\ \end{array}$$

Linear search over the possible values, taking the first one that works.

This could be optimized in many cases.



Synthesizing a Tuple of Outputs

$$\frac{\textit{choose } x.F \; \vdash \; \langle D_1 \mid t_1 \rangle \quad \textit{choose } y.D_1 \; \vdash \; \langle D_2 \mid t_2 \rangle}{\textit{choose } (x,y).F \; \vdash \; \langle D_2 \mid (t_1[y:=t_2],\; t_2) \rangle}$$

Note that y can appear inside D_1 and t_1 , but not in D_2 or t_2

Substitution of Variables

In quantifier elimination, we used a step where we replace $M \cdot x$ with y. Let F be a formula in which x occurs only in the form $M \cdot x$.

What is the corresponding rule?

$$\frac{\textit{choose } y.(F[(M \cdot x) := y] \land (M|y)) \; \vdash \; \langle D \mid t \rangle}{\textit{choose } x.F \; \vdash \; \langle D \mid t[y := t/M] \rangle}$$



Automated Checks for Specifications: Uniqueness

Suppose we wish to give a warning if the specification F allows two different solutions.

Let the variables in scope be denoted by z and consider the synthesis problem:

What is the verification condition that checks whether the solution for x is unique?

Solution is **not** unique if this PA formula is satisfiable:

$$F \wedge F[x := y] \wedge x \neq y$$

If we find such x, y, z we report z as an example input for which there are two possible outputs, x and y.

Automated Checks for Specifications: Totality

Suppose we wish to give a warning if in some cases the solution does not exist.

Let the variables in scope be denoted by z and consider the synthesis problem:

choose x. F

What is the verification condition that checks if there are cases when no solution x exists?

Check satisfiability of this PA formula:

$$\neg \exists x. F$$

If there is a satisfying value for this formula, z, report it as an example for which no solution for x exists.

