Lecture 4 Refinement, Equivalence, and Synthesis

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Local Mutable Variables

Local Variables

Assume our global variables are $V = \{x, y\}$ Program *P*:

$$x = x + 1$$
; {var y; $y = x + 3$; $z = x + y + z$ }; $x = x + z$

R(P) should be a relation between (x, y) and (x', y'). Each statement should be relation between variables in scope

$$z = x + y + z$$

is relation between x, y, z and x', y', z'Convention: consider the initial values of variables to be arbitrary R(y = x + 3; z = x + y + z) =

$$R(\{var \ y; y = x + 3; z = x + y + z\}) =$$

 $R_V(P)$ is formula for P in the scope that has the set of variables P For example,

$$R_V(x=t) = x' = t \wedge \bigwedge_{v \in V \setminus \{x\}} v' = v$$

Then define $R_V(\{var \ y; P\}) =$



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Exercise: express havoc(x) using var.

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Exercise: give transformation that lifts all variables to be global

Expressing Specifications as Commands

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Shorthand: Havoc Multiple Variables at Once

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Variables $V = \{x_1, ..., x_n\}$ Translation of $R(havoc(y_1, ..., y_m))$:

Shorthand: Havoc Multiple Variables at Once

Variables $V = \{x_1, \dots, x_n\}$ Translation of $R(havoc(y_1, \dots, y_m))$:

$$\bigwedge_{v \in V \setminus \{y_1, \dots, y_m\}} v' = v$$

Exercise: the resulting formula is the same as for:

 $havoc(y_1); \ldots; havoc(y_n)$

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Programs and Specs are Relations

program:
$$x = x + 2; y = x + 10$$
relation: $\{(x, y, z, x', y', z') \mid x' = x + 2 \land y' = x + 12 \land z' = z\}$ formula: $x' = x + 2 \land y' = x + 12 \land z' = z$

Specification:

$$z'=z\wedge (x>0\rightarrow (x'>0\wedge y'>0)$$

Adhering to specification is relation subset:

$$\{ (x, y, z, x', y', z') \mid x' = x + 2 \land y' = x + 12 \land z' = z \}$$

$$\subseteq \ \{ (x, y, z, x', y', z') \mid z' = z \land (x > 0 \to (x' > 0 \land y' > 0)) \}$$

Non-deterministic programs are a way of writing specifications

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Corresponding program:



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$$z'=z\wedge x'>0\wedge y'>0$$

Corresponding program:

```
havoc(x, y); assume(x > 0 \land y > 0)
```

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Program variables $V = \{x, y, z\}$ Formula for relation (talks only about resulting state):

$$z'=z\wedge x'>0\wedge y'>0$$

Corresponding program:

$$havoc(x, y)$$
; $assume(x > 0 \land y > 0)$

Formula for relation:

$$z' = z \land x' > x \land y' > y$$

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Corresponding program? Use local variables to store initial values.

{ var x0; var y0;

$$x0 = x; y0 = y;$$

 $havoc(x,y);$
 $assume(x > x0 \&\& y > y0)$
}

Writing Specs Using Havoc and Assume

Global variables
$$V = \{x_1, \dots, x_n\}$$

Specification
 $F(x_1, \dots, x_n, x'_1, \dots, x'_n)$

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Writing Specs Using Havoc and Assume

Global variables
$$V = \{x_1, \dots, x_n\}$$

Specification
 $F(x_1, \dots, x_n, x_1', \dots, x_n')$

Becomes

{ var
$$y_1, ..., y_n$$
;
 $y_1 = x_1; ...; y_n = x_n$;
 $havoc(x_1, ..., x_n)$;
 $assume(F(y_1, ..., y_n, x_1, ..., x_n))$ }

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Program Refinement and Equivalence

For two programs, define **refinement** $P_1 \sqsubseteq P_2$ iff

$$R(P_1) \rightarrow R(P_2)$$

is a valid formula.

(Some books use the opposite meaning of \sqsubseteq .) As usual, $P_2 \sqsupseteq P_1$ iff $P_1 \sqsubseteq P_2$.

• $P_1 \sqsubseteq P_2$ iff $\rho(P_1) \subseteq \rho(P_2)$

Define **equivalence** $P_1 \equiv P_2$ iff $P_1 \sqsubseteq P_2 \land P_2 \sqsubseteq P_1$

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$$P_1 \equiv P_2$$
 iff $\rho(P_1) = \rho(P_2)$

Example for $V = \{x, y\}$

{*var* x0; *havoc*(x); *assume*(x > x0)} \supseteq (x = x + 1)

Proof: Use R to compute formulas for both sides and simplify.

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{*var*
$$x0$$
; *havoc*(x); *assume*($x > x0$)} \supseteq ($x = x + 1$)

Proof: Use R to compute formulas for both sides and simplify.

$$x' = x + 1 \rightarrow x' > x$$

Stepwise Refinement Methodology

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Start form a possibly non-deterministic specification P_0 Refine the program until it becomes deterministic and efficiently executable.

$$P_0 \sqsupseteq P_1 \sqsupseteq \ldots \sqsupseteq P_n$$

Example:

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In the last step program equivalence holds as well

Monotonicity with Respect to Refinement

Theorem: if $P_1 \sqsubseteq P_2$ then $(P_1; P) \sqsubseteq (P_2; P)$ Theorem: if $P_1 \sqsubseteq P_2$ then $(P; P_1) \sqsubseteq (P; P_2)$ Theorem: if $P_1 \sqsubseteq P_2$ and $P'_1 \sqsubseteq P'_2$ then

$$(if (*)P_1 else P'_1) \sqsubseteq (if (*)P_2 else P'_2)$$

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Checking Commutativity and Idempotence

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Associativity of Commands

Under what conditions on commands c_1, c_2 is

$$c_1; (c_2; c_3) \equiv (c_1; c_2); c_3$$

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Commutativity of Commands

Under what conditions on commands c_1, c_2 is

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c_1; c_2 \equiv c_2; c_1
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In general, when the resulting relations are equal and formulas equivalent, i.e. iff

$$R(c_1;c_2) \iff R(c_2;c_1)$$

is a valid formula (true for all variables). Example: does this hold?

$$(x = x + 1; y = x + 2) \equiv (y = x + 2; x = x + 1)$$

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Show formulas for each sides

Show the formula for each example and check if the commutativity equivalence holds

Example 1:

$$(x = 2*x+7*z; y = 5*y+z) \equiv (y = 5*y+z; x = 2*x+7*z)$$

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Can you state a generalization of the above example?

Show the formula for each example and check if the commutativity equivalence holds

Example 1:

$$(x = 2*x+7*z; y = 5*y+z) \equiv (y = 5*y+z; x = 2*x+7*z)$$

Can you state a generalization of the above example? Example 2:

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Requires knowing properties of +.

Preserving Domain in Refinement

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Preserving Domain

It is not interesting program development step $P \sqsupseteq P'$ is P' is false, or is false for most inputs. Example:

$$(havoc(x); assume(x + x = y)) \supseteq (assume(y = 6); x = 3)$$

When doing refinement $P \supseteq P'$, which ensures

$$R(P') \rightarrow R(P)$$

we also wish to preserve the *domain* of the relation between \bar{x}, \bar{x}'

- if P has some execution from \bar{x} ending in x'
- then P' should also have some execution, ending in some x" (even if it has fewer choices)

$$(\exists \bar{x}'.R(P)) \rightarrow (\exists \bar{x}''.R(P'))$$

This is weaker than $R(P) \rightarrow R(P')$. Definition: domain formula of P is the formula $\exists \bar{x}'.R(P)$

Consider our example $P \sqsupseteq P'$

 $(havoc(x); assume(x + x = y)) \supseteq (assume(y = 6); x = 3)$

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Now consider the right hand side:

domain of P is

Consider our example $P \supseteq P'$

 $(havoc(x); assume(x + x = y)) \supseteq (assume(y = 6); x = 3)$

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Now consider the right hand side:

- domain of P is $\exists x', y'.x' + x' = y \land y' = y$
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- domain of P is: $\exists x', y'.x' = 3 \land y' = 6 \land y' = y$
- equivalent to: y = 6

Does domain formula of P' imply the domain formula of P?

Preserving Domain: Exercise

Given P:

$$havoc(x)$$
; $assume(x + x = y)$

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Find P_1 and P_2 such that

- $\blacktriangleright P \sqsupseteq P_1 \sqsupseteq P_2$
- no two programs among P, P_1, P_2 are equivalent
- programs P, P_1 and P_2 have equivalent domains
- the relation described by P_2 is a partial function

Complete Functional Synthesis

Synthesis from Relations

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Complete Functional Synthesis

Domain-preserving refinement algorithm that produces a partial function

- assignment: res = choose x. F
- corresponds to: {var x; assume(F); res = x}
- we refine it preserving domain into: assume(D); res = t (where t does not have 'choose')

More abstractly, given formula F and variable x find

formula D

term t not containing x

such that, for all free variables:

• $D \rightarrow F[x := t]$ (t is a term such that refinement holds)

• $D \iff \exists x.F$ (*D* is the domain, says when *t* is correct)

Consequence of the definition: $D \iff F[x := t]$

See Comfusy Examples on the Web

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From Quantifier Elimination to Synthesis

Quantifier Elimination

If \bar{y} is a tuple of variables not containing x, then

$$\exists x.(x = t(\bar{y}) \land F(x, \bar{y})) \iff F(t(\bar{y}), \bar{y})$$

Synthesis

choose
$$x.(x = t(\bar{y}) \land F(x, \bar{y}))$$

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gives:

- precondition $F(t(\bar{y}), \bar{y})$, as before, but also
- program that realizes x, in this case, $t(\bar{y})$

Handling Disjunctions

We had

 $\exists x.(F_1(x) \lor F_2(x))$

is equivalent to

 $(\exists x.F_1(x)) \lor (\exists x.F_2(x))$

Now:

choose
$$x.(F_1(x) \lor F_2(x))$$

becomes:

if
$$(D_1)$$
 (choose $x.F_1(x)$) else (choose $x.F_2(x)$)

where D_1 is the domain, equivalent to $\exists x.F_1(x)$ and computed while computing *choose* $x.F_1(x)$.

Framework for Synthesis Procedures

We define the framework as a transformation

- from specification formula F to
- the maximal domain D where the result x can be found, and the program t that computes the result

 $\langle D \mid t \rangle$ denotes: the domain (formula) D and program (term) tMain transformation relation \vdash

choose x.F
$$\vdash \langle D \mid t \rangle$$

means

• $D \rightarrow F[x := t]$ (*t* is a term such that refinement holds) • $D \iff \exists x.F$ (*D* is the domain, says when *t* is correct)

Rule for Synthesizing Conditionals

$$\frac{\textit{choose } x.F_1 \vdash \langle D_1 \mid t_1 \rangle \quad \textit{choose } x.F_2 \vdash \langle D_2 \mid t_2 \rangle}{\textit{choose } x.(F_1 \lor F_2) \ \vdash \ \langle D_1 \lor D_2 \mid \textit{if } (D_1) \ t_1 \textit{ else } t_2 \rangle}$$

To synthesize the thing below the — , synthesize the things above and put the pieces together.

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Test Terms Methods for Presburger Arithmetic Synthesis

Recall that the most complex step in QE for PA was replacing

 $\exists x.F_1(x)$

with

$$\bigvee_{k=1}^{L}\bigvee_{i=1}^{N}F_{1}(a_{k}+i)$$

Now we transform *choose* x. $F_1(x)$ first into:

choose
$$x$$
. $\bigvee_{k=1}^{L}\bigvee_{i=1}^{N}(x=a_{k}+i\wedge F_{1}(x))$

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Then apply:

Test Terms Methods for Presburger Arithmetic Synthesis

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 $\exists x.F_1(x)$

with

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$$x$$
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Then apply:

- rule for conditionals
- one-point rule

Synthesis using Test Terms

choose x.
$$\bigvee_{k=1}^{L}\bigvee_{i=1}^{N}(x=a_{k}+i\wedge F_{1})$$

produces the same precondition as the result of QE, and the generated term is:

$$if (F_1[x := a_1 + 1]) a_1 + 1$$

$$elseif (F_1[x := a_1 + 2]) a_1 + 2$$

...

$$elseif (F_1[x := a_k + i]) a_k + i$$

...

$$elseif (F_1[x := a_L + N]) a_L + N$$

Linear search over the possible values, taking the first one that works.

This could be optimized in many cases.

Synthesizing a Tuple of Outputs

$$\frac{\textit{choose } x.F \vdash \langle D_1 \mid t_1 \rangle \quad \textit{choose } y.D_1 \vdash \langle D_2 \mid t_2 \rangle}{\textit{choose } (x,y).F \vdash \langle D_2 \mid (t_1[y := t_2], \ t_2) \rangle}$$

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Note that y can appear inside D_1 and t_1 , but not in D_2 or t_2

In quantifier elimination, we used a step where we replace $M\cdot y$ with x

$$\frac{\textit{choose } x.F \ \vdash \ \langle D_1 \mid t_1 \rangle \quad \textit{choose } y.D_1 \ \vdash \ \langle D_2 \mid t_2 \rangle}{\textit{choose } (x,y).F \ \vdash \ \langle D_2 \mid (t_1[y := t_2], \ t_2) \rangle}$$

Automated Checks for Specifications: Uniqueness

Suppose we wish to give a warning if the specification F allows two different solutions.

Let the variables in scope be denoted by *a* and consider the synthesis problem:

choose x. F

What is the verification condition that checks whether the solution for x is unique?

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What is the verification condition that checks whether the solution for x is unique? Solution is **not** unique if this PA formula is satisfiable:

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Automated Checks for Specifications: Uniqueness

Suppose we wish to give a warning if the specification F allows two different solutions.

Let the variables in scope be denoted by *a* and consider the synthesis problem:

choose x. F

What is the verification condition that checks whether the solution for x is unique? Solution is **not** unique if this PA formula is satisfiable:

$$F \wedge F[y := x] \wedge x \neq y$$

If we find such x, y, a we report them as an example that, for input a, there are two possible outputs, x and y

Automated Checks for Specifications: Totality

Suppose we wish to give a warning if in some cases the solution does not exist.

Let the variables in scope be denoted by *a* and consider the synthesis problem:

choose x. F

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What is the verification condition that checks if there are cases when no solution x exists?

Automated Checks for Specifications: Totality

Suppose we wish to give a warning if in some cases the solution does not exist.

Let the variables in scope be denoted by *a* and consider the synthesis problem:

choose x. F

What is the verification condition that checks if there are cases when no solution x exists? Check satisfiability of this PA formula:

 $\neg \exists x.F$

If there is a solution a, report it as an example for which no solutions exist.

Further Topics

- demo
- handling equality and the consequence of Euclid's algorithm

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synthesis for sets with cardinality bounds

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