

Lecture 4

Refinement. Synthesis Procedures

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Local Variables

Global variables $V = \{x, z\}$

Program P :

$x = x + 1; \{ \text{var } y; y = x + 3; z = x + y + z \}; x = x + z$

$R(P)$ should be a relation between (x, z) and (x', z') .

Each statement should be relation between variables in scope

$$z = x + y + z$$

is relation between x, y, z and x', y', z'

Convention: consider the initial values of variables to be arbitrary

$$R(y = x + 3; z = x + y + z) = \exists y, y'. y' = x + 3 \wedge z' = 2x + 3 + z \wedge x' = x$$

$$R(\{ \text{var } y; y = x + 3; z = x + y + z \}) = \exists y, y'. y' = x + 3 \wedge z' = 2x + 3 + z \wedge x' = x$$

Local Variable Translation

\mathcal{R} : programs \rightarrow formulas

$R_V(P)$ is formula for P in the scope that has the set of variables P
For example,

$$R_V(x = t) = x' = t \wedge \bigwedge_{v \in V \setminus \{x\}} v' = v$$

Then define

$$R_V(\{\text{var } y; P\}) = \exists y'. y. R_{V \cup \{y\}}(P)$$

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Exercise: express $havoc(x)$ using var .

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Exercise: express $\text{havoc}(x)$ using var .

$$V = \{x, z\}$$

$$\begin{aligned} z' = z & \iff R_V(\text{havoc}(x)) \iff R_V(\{\text{var } y; \underbrace{x = y}_{\text{scope}}\}) \\ & \iff \exists y, \exists y'. (x' = y \wedge y' = y \wedge z' = z) \\ & \iff \exists y. x' = y \wedge z' = z \\ & \iff z' = z \end{aligned}$$

Havoc Multiple Variables at Once

Variables $V = \{x_1, \dots, x_n\}$

Translation of $R(\text{havoc}(y_1, \dots, y_m))$:

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Translation of $R(\text{havoc}(y_1, \dots, y_m))$:

$$\bigwedge_{v \in V \setminus \{y_1, \dots, y_m\}} v' = v$$

Exercise: the resulting formula is the same as for:

$$\text{havoc}(y_1); \dots; \text{havoc}(y_n)$$

Programs and Specs are Relations

\mathcal{P} program: $x = x + 2; y = x + 10$

$\mathcal{S}(\mathcal{P})$ relation: $\{(x, y, z, x', y', z') \mid x' = x + 2 \wedge y' = x + 12 \wedge z' = z\}$

$\mathcal{R}(\mathcal{P})$ formula: $x' = x + 2 \wedge y' = x + 12 \wedge z' = z$

Specification:

$$z' = z \wedge (x > 0 \rightarrow (x' > 0 \wedge y' > 0))$$

Adhering to specification is relation subset:

$$\begin{aligned} & \{(x, y, z, x', y', z') \mid x' = x + 2 \wedge y' = x + 12 \wedge z' = z\} \\ \subseteq & \{(x, y, z, x', y', z') \mid z' = z \wedge (x > 0 \rightarrow (x' > 0 \wedge y' > 0))\} \end{aligned}$$

Non-deterministic programs are a way of writing specifications

Writing Specs Using Havoc and Assume: Examples

Program variables $V = \{x, y, z\}$

Formula for relation (talks only about resulting state):

$$z' = z \wedge x' > 0 \wedge y' > 0$$

Corresponding program:

Writing Specs Using Havoc and Assume: Examples

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Corresponding program:

```
havoc(x, y); assume(x > 0  $\wedge$  y > 0)
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Program variables $V = \{x, y, z\}$

Formula for relation (talks only about resulting state):

$$z' = z \wedge x' > 0 \wedge y' > 0$$

Corresponding program:

havoc(x, y); *assume*($x > 0 \wedge y > 0$)

Formula for relation:

$$z' = z \wedge x' > x \wedge y' > y$$

Corresponding program?

Writing Specs Using Havoc and Assume: Examples

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Corresponding program?

Use local variables to store initial values.

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Formula for relation:

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Corresponding program?

Use local variables to store initial values.

```
{ var x0; var y0; var z0;  
  x0 = x; y0 = y; z0 = z;  
  havoc(x,y,z)  
  assume(x > x0 && y > y0) && z = z0  
}
```

Writing Specs Using Havoc and Assume

Global variables $V = \{x_1, \dots, x_n\}$

Specification

$$F(x_1, \dots, x_n, x'_1, \dots, x'_n)$$

Becomes

e'

Writing Specs Using Havoc and Assume

Global variables $V = \{x_1, \dots, x_n\}$

Specification

$$F(x_1, \dots, x_n, x'_1, \dots, x'_n)$$

Becomes

```
{ var  $y_1, \dots, y_n$ ;  
   $y_1 = x_1; \dots; y_n = x_n$ ;  
  havoc( $x_1, \dots, x_n$ );  
  assume( $F(y_1, \dots, y_n, x_1, \dots, x_n)$ ) }
```

uq

Program Refinement

For two programs, define $P_1 \sqsubseteq P_2$ iff

$$R(P_1) \rightarrow R(P_2)$$

is a valid formula. As usual, $P_2 \sqsupseteq P_1$ iff $P_1 \sqsubseteq P_2$.

- ▶ $P_1 \sqsubseteq P_2$ iff $\rho(P_1) \subseteq \rho(P_2)$

Define $P_1 \equiv P_2$ iff $P_1 \sqsubseteq P_2 \wedge P_2 \sqsubseteq P_1$

- ▶ $P_1 \equiv P_2$ iff $\rho(P_1) = \rho(P_2)$

Example for $V = \{x, y\}$

$$\{\text{var } x_0; \overset{x_0 = x;}{y} \text{havoc}(x); \text{assume}(x > x_0)\} \sqsupseteq (x = x + 1)$$

Proof: Use R to compute formulas for both sides and simplify them.

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Example for $V = \{x, y\}$

$$\{\text{var } x_0; \text{havoc}(x); \text{assume}(x > x_0)\} \sqsupseteq (x = x + 1)$$

Proof: Use R to compute formulas for both sides and simplify them.

$$x' = x + 1 \rightarrow x' > x$$

Stepwise Refinement Methodology

Start from a possibly non-deterministic specification P_0
Refine the program until it becomes deterministic and efficiently executable.

$$P_0 \sqsupseteq P_1 \sqsupseteq \dots \sqsupseteq P_n$$

Example:

$$\begin{aligned} & \text{havoc}(x); \text{assume}(x > 0); \text{havoc}(y); \text{assume}(\overset{y > x}{\cancel{x > y}}) \\ \sqsupseteq & \text{havoc}(x); \text{assume}(x > 0); y = x + 1 \\ \sqsupseteq & x = 42; y = x + 1 \\ \sqsupseteq & x = 42; y = 43 \end{aligned}$$

In the last step program equivalence holds as well

Monotonicity with Respect to Refinement

Theorem: if $P_1 \sqsubseteq P_2$ then $(P_1; P) \sqsubseteq (P_2; P)$

Theorem: if $P_1 \sqsubseteq P_2$ then $(P; P_1) \sqsubseteq (P; P_2)$

Theorem: if $P_1 \sqsubseteq P_2$ and $P'_1 \sqsubseteq P'_2$ then

$$(if (*)P_1 \text{ else } P'_1) \sqsubseteq (if (*)P_2 \text{ else } P'_2)$$

Preserving Domain

It is not interesting program development step $P \sqsupseteq P'$ if P' is false, or is false for most inputs.

Example:

$$(havoc(x); assume(x + x = y)) \sqsupseteq (assume(y = 6); x = 3)$$

$x' + x' = y \wedge y' = y$ ← $y' = y \wedge y' = 6 \quad \wedge \quad x' = 3$

When doing refinement $P \sqsupseteq P'$, which ensures

$$R(P') \rightarrow R(P) \quad \begin{matrix} P \\ \text{dom}(S(P)) \end{matrix}$$

$\text{dom}(r) = \{x \mid \exists x'. (x, x') \in r\}$

we also wish to preserve the *domain* of the relation between \bar{x}, \bar{x}'

- ▶ if P has some execution from \bar{x} ending in x'
- ▶ then P' should also have some execution, ending in some x'' (even if it has fewer choices)

$$(\exists \bar{x}'. R(P)) \rightarrow (\exists \bar{x}' \bullet R(P'))$$

This is weaker than $R(P) \rightarrow R(P')$.

Definition: domain formula of P is the formula $\exists \bar{x}'. R(P)$

Domains in the Example

Consider our example $P \sqsubseteq P'$

$$(havoc(x); assume(x + x = y)) \sqsubseteq (assume(y = 6); x = 3)$$

► $R(P) =$

Domains in the Example

Consider our example $P \sqsubseteq P'$

$$(havoc(x); assume(x + x = y)) \sqsubseteq (assume(y = 6); x = 3)$$

- ▶ $R(P) = x' + x' = y \wedge y' = y$
- ▶ $R(P') =$

Domains in the Example

Consider our example $P \sqsupseteq P'$

$$(havoc(x); assume(x + x = y)) \sqsupseteq (assume(y = 6); x = 3)$$

- ▶ $R(P) = x' + x' = y \wedge y' = y$
- ▶ $R(P') = x' = 3 \wedge y' = 6 \wedge y' = y$

Does $P \sqsupseteq P'$ really hold?

Now consider the right hand side:

- ▶ domain of P is

Domains in the Example

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- ▶ $R(P') = x' = 3 \wedge y' = 6 \wedge y' = y$

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Now consider the right hand side:

- ▶ domain of P is $\exists x', y'. x' + x' = y \wedge y' = y$
- ▶ equivalent to:

Domains in the Example

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$$(havoc(x); assume(x + x = y)) \sqsupseteq (assume(y = 6); x = 3)$$

- ▶ $R(P) = x' + x' = y \wedge y' = y$
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Does $P \sqsupseteq P'$ really hold?

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- ▶ domain of P is $\exists x', y'. x' + x' = y \wedge y' = y$
- ▶ equivalent to: $y \% 2 = 0$
- ▶ domain of P' is:

Domains in the Example

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Does $P \sqsupseteq P'$ really hold?

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- ▶ domain of P is $\exists x', y'. x' + x' = y \wedge y' = y$
- ▶ equivalent to: $y \% 2 = 0$
- ▶ domain of P' is: $\exists x', y'. x' = 3 \wedge y' = 6 \wedge y' = y$
- ▶ equivalent to: $y = 6$

Does domain formula of P' imply the domain formula of P ?

Preserving Domain: Exercise

$$R(P) = x' + x' \geq y' \wedge y' = y$$

domain: $\exists x', y'. R(P) \Leftrightarrow \exists x'. 2x' \geq y$ true $\rightarrow x+x \geq y$

Given P :

$$\text{havoc}(x); \text{assume}(x + x \geq y)$$

Find P_1 and P_2 such that

P_1 :

$$\text{havoc}(x); \text{assume}(2x = y)$$

$$2x = y \rightarrow 2x \geq y$$

▶ $P \sqsupseteq P_1 \sqsupseteq P_2$

▶ no two programs among P, P_1, P_2 are equivalent

▶ programs P, P_1 and P_2 have equivalent domains

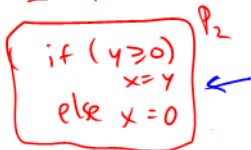
▶ the relation described by P_2 is a partial function

$$P_1: \text{havoc}(x); \text{assume}(x+x-1 \geq y) \sqsubseteq P$$

$$P_2 \sqsubseteq P_1$$

$$x = \max(0, y)$$

$$R(P_2): y' = y \wedge (y \geq 0 \rightarrow x' = y) \wedge (y < 0 \rightarrow x' = 0)$$



Complete Functional Synthesis

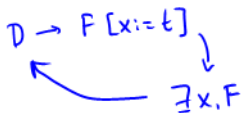
Domain-preserving refinement algorithm that produces a partial function

$\exists x.F$

- ▶ assignment: **res = choose x. F**
- ▶ corresponds to: $\{\text{var } x; \text{assume}(F); \text{res} = x\}$
- ▶ we refine it preserving domain into: **assume(D); res = t**
(where t does not have 'choose')

More abstractly, given formula F and variable x find

- ▶ formula D
- ▶ term t not containing x



such that, for all free variables:

- ▶ $D \rightarrow F[x := t]$ (t is a term such that refinement holds)
- ▶ $D \iff \exists x.F$ (D is the domain, says when t is correct)

Consequence of the definition: $D \iff F[x := t]$

See Comfusy Examples on the Web

From Quantifier Elimination to Synthesis

Quantifier Elimination

If \bar{y} is a tuple of variables not containing x , then

$$\exists x.(x = t(\bar{y}) \wedge F(x, \bar{y})) \iff F(t(\bar{y}), \bar{y})$$

Synthesis

choose $x.(x = t(\bar{y}) \wedge F(x, \bar{y}))$

gives:

- ▶ precondition $F(t(\bar{y}), \bar{y})$, as before, but also
- ▶ program that realizes x , in this case, $t(\bar{y})$

Handling Disjunctions

We had

$$\exists x.(F_1(x) \vee F_2(x))$$

is equivalent to

$$(\exists x.F_1(x)) \vee (\exists x.F_2(x))$$

Now:

$$\textit{choose } x.(F_1(x) \vee F_2(x))$$

becomes:

$$\textit{if } (D_1) \textit{ (choose } x.F_1(x)) \textit{ else (choose } x.F_2(x))$$

where D_1 is the domain, equivalent to $\exists x.F_1(x)$ and computed while computing $\textit{choose } x.F_1(x)$.

Framework for Synthesis Procedures

We define the framework as a transformation

- ▶ from specification formula F to
- ▶ the maximal domain D where the result x can be found, and the program t that computes the result

$\langle D \mid t \rangle$ denotes: the domain (formula) D and program (term) t

Main transformation relation \vdash

$$\text{choose } x.F \vdash \langle D \mid t \rangle$$

means

- ▶ $D \rightarrow F[x := t]$ (t is a term such that refinement holds)
- ▶ $D \iff \exists x.F$ (D is the domain, says when t is correct)

Rule for Synthesizing Conditionals

$$\frac{\text{choose } x.F_1 \vdash \langle D_1 \mid t_1 \rangle \quad \text{choose } x.F_2 \vdash \langle D_2 \mid t_2 \rangle}{\text{choose } x.(F_1 \vee F_2) \vdash \langle D_1 \vee D_2 \mid \text{if } (D_1) t_1 \text{ else } t_2 \rangle}$$

To synthesize the thing below the — , synthesize the things above and put the pieces together.

Test Terms Methods for Presburger Arithmetic Synthesis

Recall that the most complex step in QE for PA was replacing

$$\exists x.F_1(x)$$

with

$$\bigvee_{k=1}^L \bigvee_{i=1}^N F_1(a_k + i)$$

Now we transform *choose* $x.F_1(x)$ first into:

$$\text{choose } x. \bigvee_{k=1}^L \bigvee_{i=1}^N (x = a_k + i \wedge F_1(x))$$

Then apply:

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$$\text{choose } x. \bigvee_{k=1}^L \bigvee_{i=1}^N (x = a_k + i \wedge F_1(x))$$

Then apply:

- ▶ rule for conditionals
- ▶ one-point rule

Synthesis using Test Terms

$$\text{choose } x. \bigvee_{k=1}^L \bigvee_{i=1}^N (x = a_k + i \wedge F_1)$$

produces the same precondition as the result of QE, and the generated term is:

if ($F_1[x := a_1 + 1]$) $a_1 + 1$
elseif ($F_1[x := a_1 + 2]$) $a_1 + 2$
...
elseif ($F_1[x := a_k + i]$) $a_k + i$
...
elseif ($F_1[x := a_L + N]$) $a_L + N$

Linear search over the possible values, taking the first one that works.

This could be optimized in many cases—consider a project.

Synthesizing a Tuple of Outputs

$$\frac{\text{choose } x.F \vdash \langle D_1 \mid t_1 \rangle \quad \text{choose } y.D_1 \vdash \langle D_2 \mid t_2 \rangle}{\text{choose } (x, y).F \vdash \langle D_2 \mid (t_1[y := t_2], t_2) \rangle}$$

Note that y can appear inside D_1 and t_1 , but not in D_2 or t_2

Automated Checks for Specifications: Uniqueness

Suppose we wish to give a warning if the specification F allows two different solutions.

Let the variables in scope be denoted by a and consider the synthesis problem:

choose x . F

What is the verification condition that checks whether the solution for x is unique?

Automated Checks for Specifications: Uniqueness

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Let the variables in scope be denoted by α and consider the synthesis problem:

choose x . F

What is the verification condition that checks whether the solution for x is unique?

Solution is **not** unique if this PA formula is satisfiable:

$$\exists \alpha. \exists x_1, x_2. F[x := x_1] \wedge F[x := x_2] \wedge x_1 \neq x_2$$

Automated Checks for Specifications: Uniqueness

Suppose we wish to give a warning if the specification F allows two different solutions.

Let the variables in scope be denoted by a and consider the synthesis problem:

$$\text{choose } x. F$$

What is the verification condition that checks whether the solution for x is unique?

Solution is **not** unique if this PA formula is satisfiable:

$$F \wedge F[y := x] \wedge x \neq y$$

If we find such x, y, a we report them as an example that, for input a , there are two possible outputs, x and y

Automated Checks for Specifications: Totality

Suppose we wish to give a warning if in some cases the solution does not exist.

Let the variables in scope be denoted by a and consider the synthesis problem:

$\text{choose } x. F \rightsquigarrow \langle D | t \rangle$

What is the verification condition that checks if there are cases when no solution x exists?

$$\forall a. \underbrace{\exists x. F}_{\equiv D}$$

$\neg D$

Automated Checks for Specifications: Totality

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Let the variables in scope be denoted by a and consider the synthesis problem:

$$\text{choose } x. F$$

What is the verification condition that checks if there are cases when no solution x exists?

Check satisfiability of this PA formula:

$$\neg \exists x. F$$

If there is a solution a , report it as an example for which no solutions exist.

Further Topics

- ▶ demo
- ▶ handling equality and the consequence of Euclid's algorithm
- ▶ synthesis for sets with cardinality bounds

